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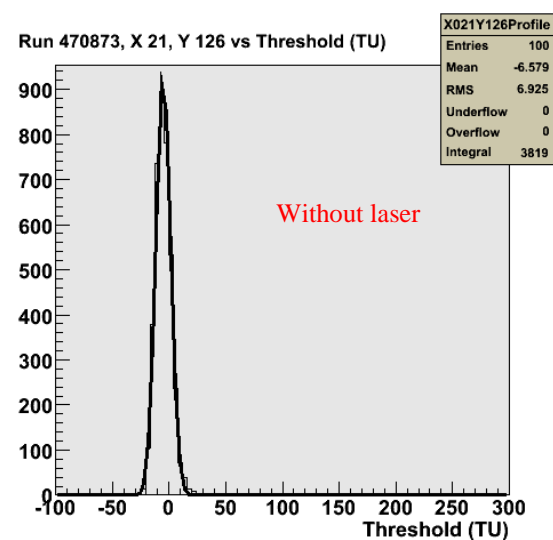
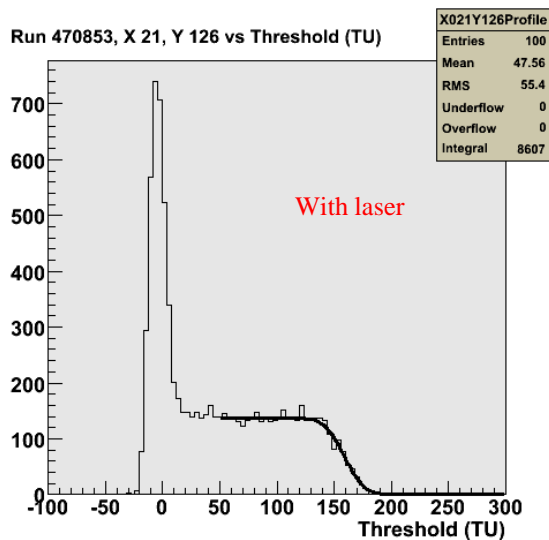
# Various sensor test results

Paul Dauncey

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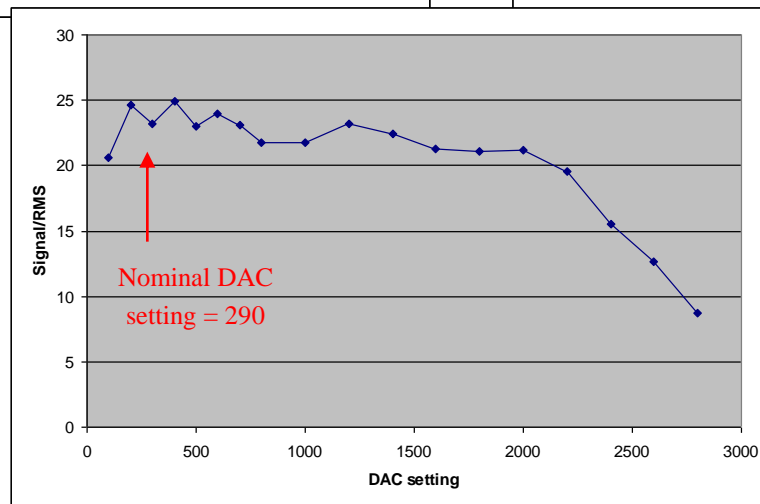
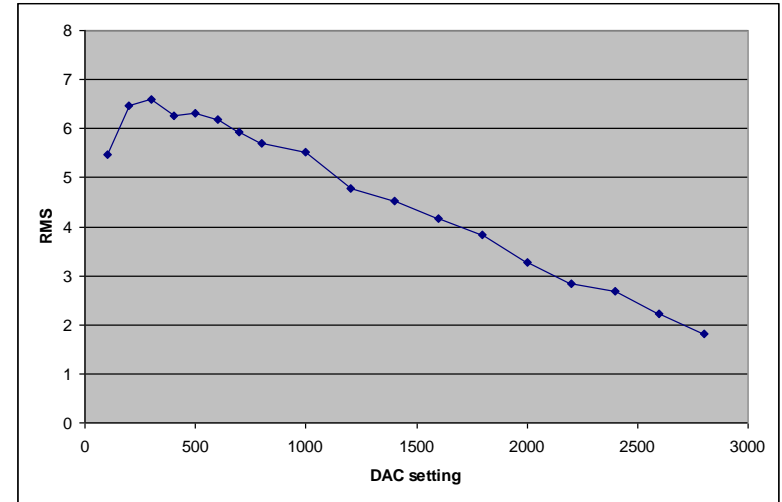
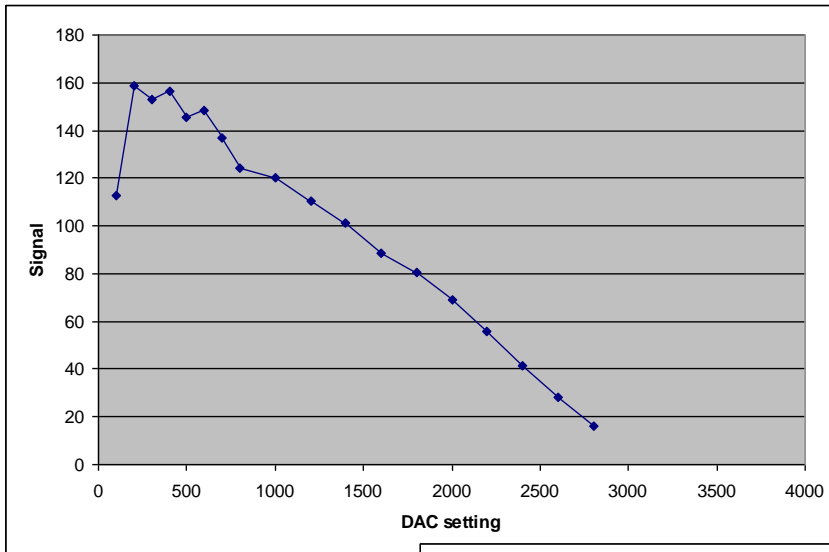
# Working point

- Jamie determined working point of the bias DACs from simulation
- Should check these explicitly
  - Use laser to measure signal from threshold scan
  - Use threshold scan without laser to determine noise
  - Take ratio as figure of merit
  - Can only do one pixel at a time as uses laser

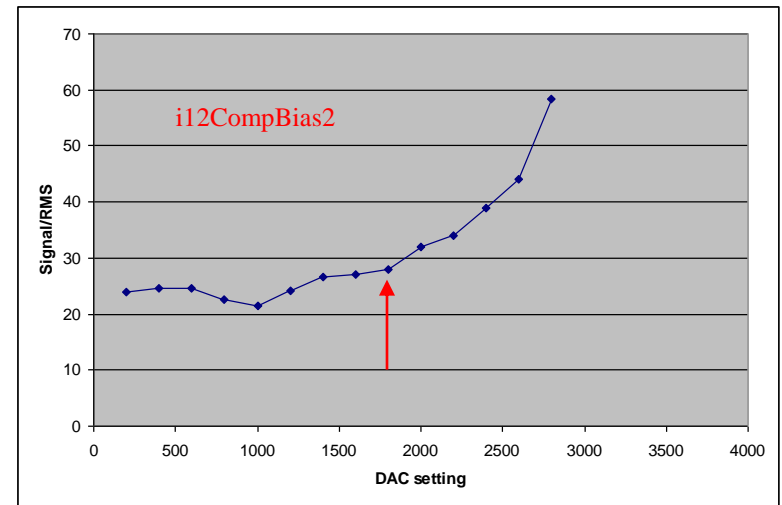
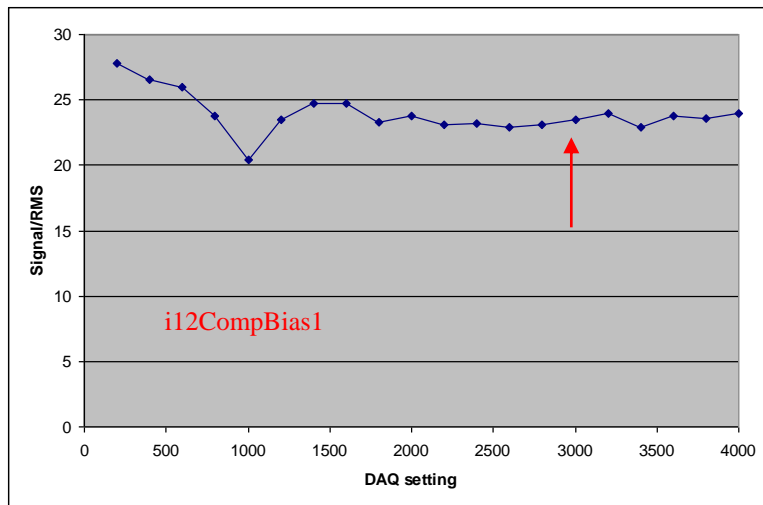
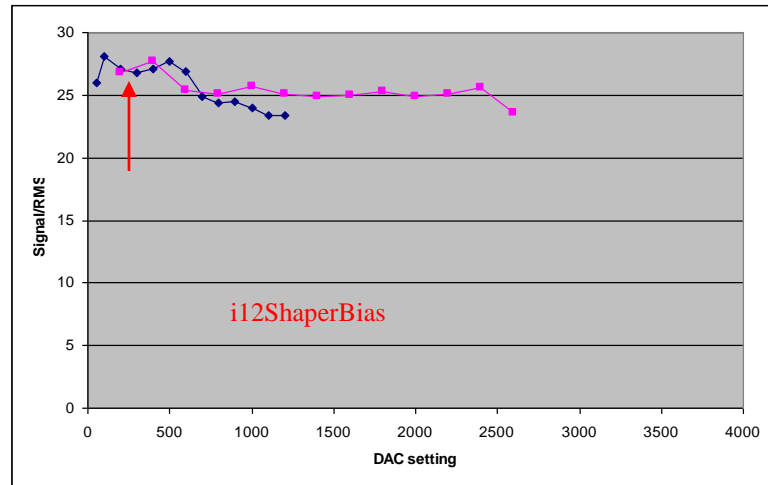
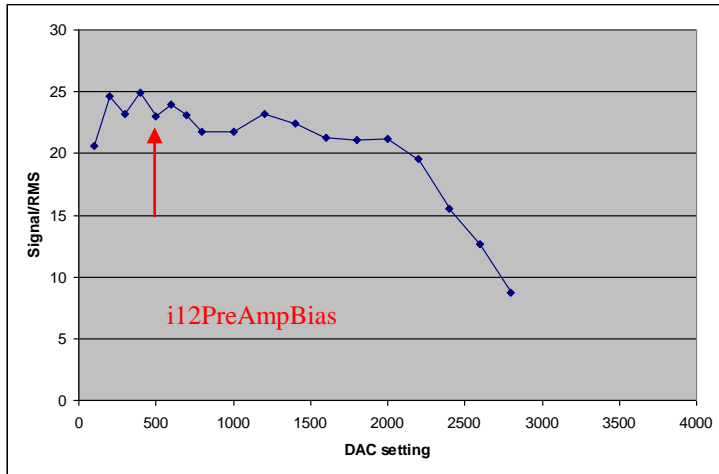


# i12PreAmpBias

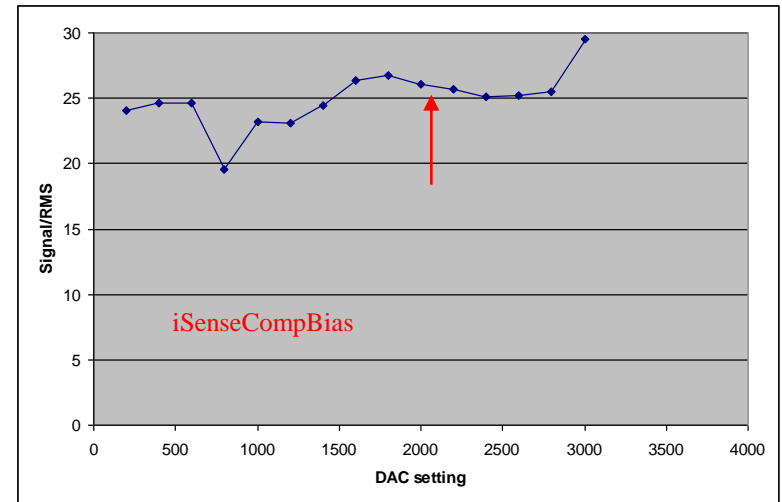
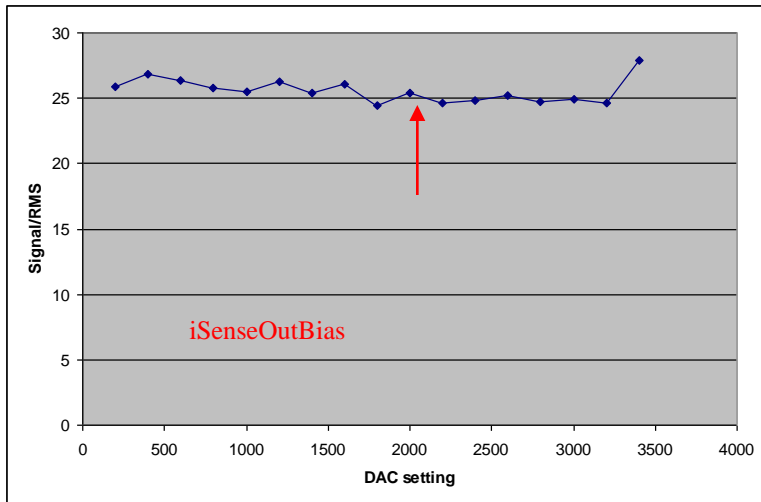
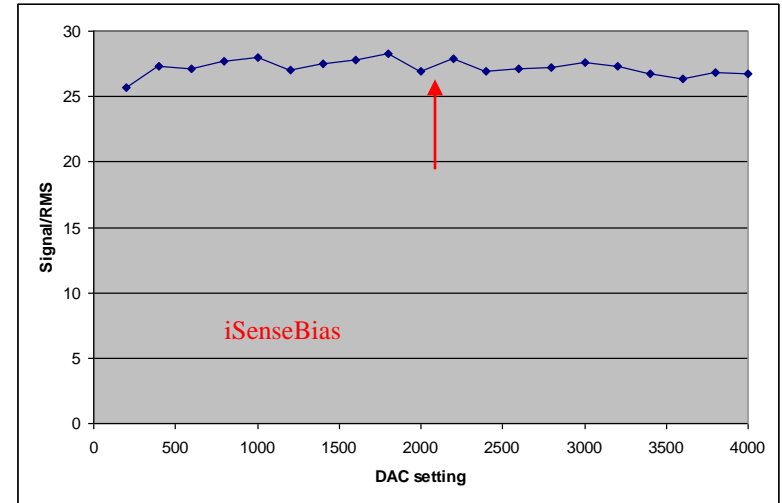
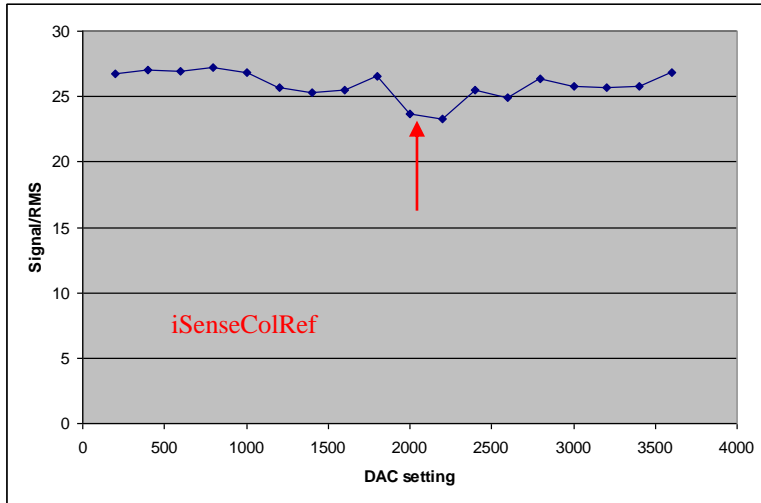
- Example of one of the DAC biases



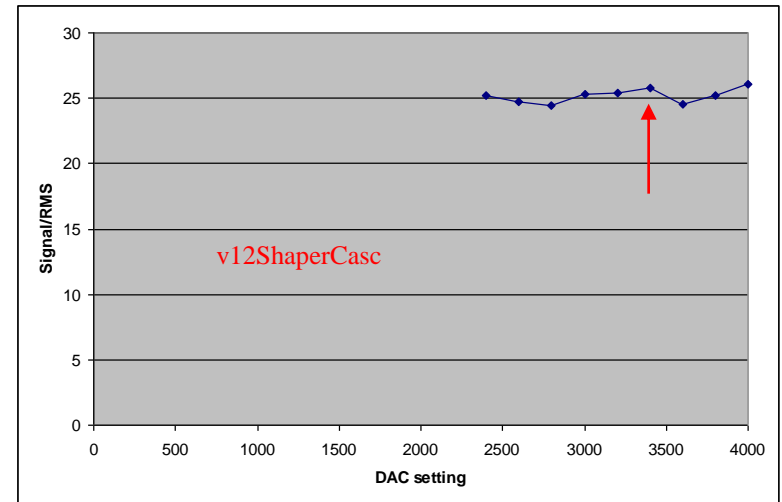
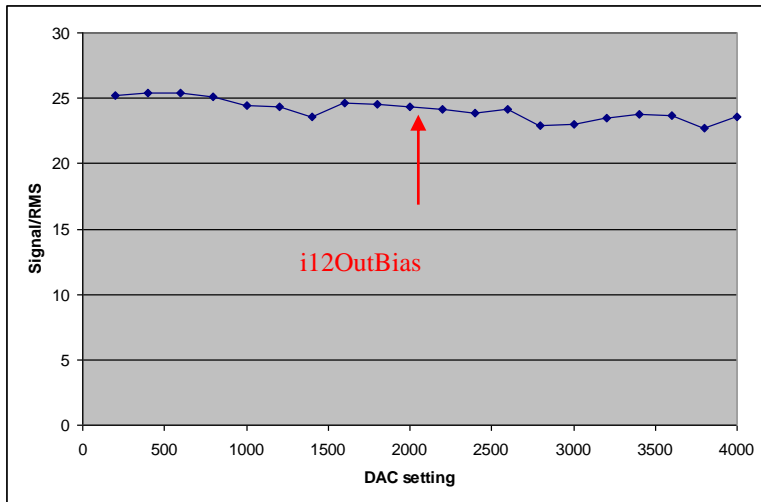
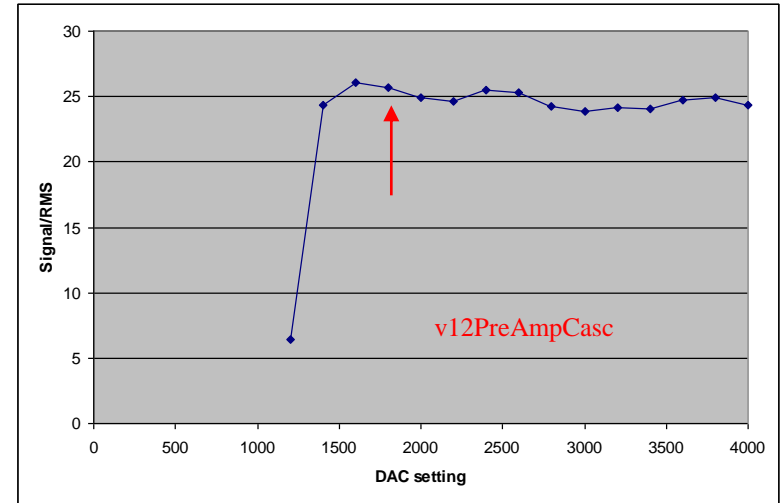
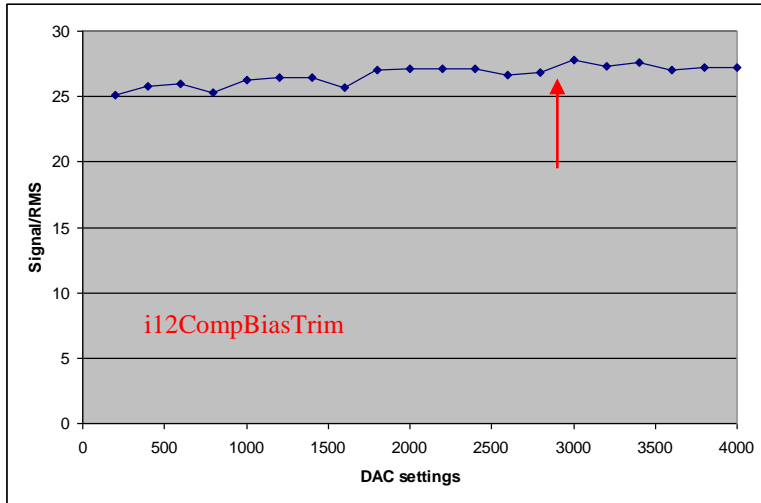
# Full set of biases; part I



# Part II

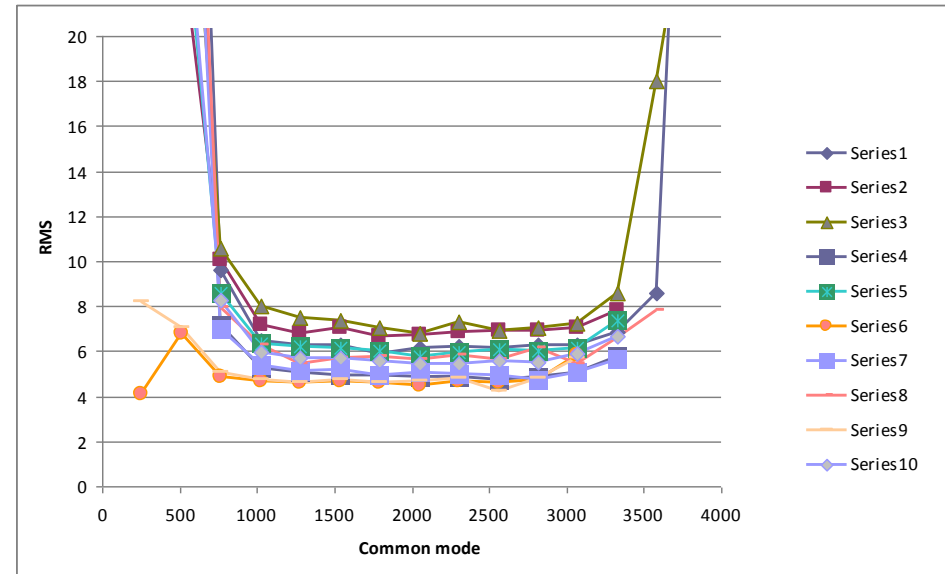
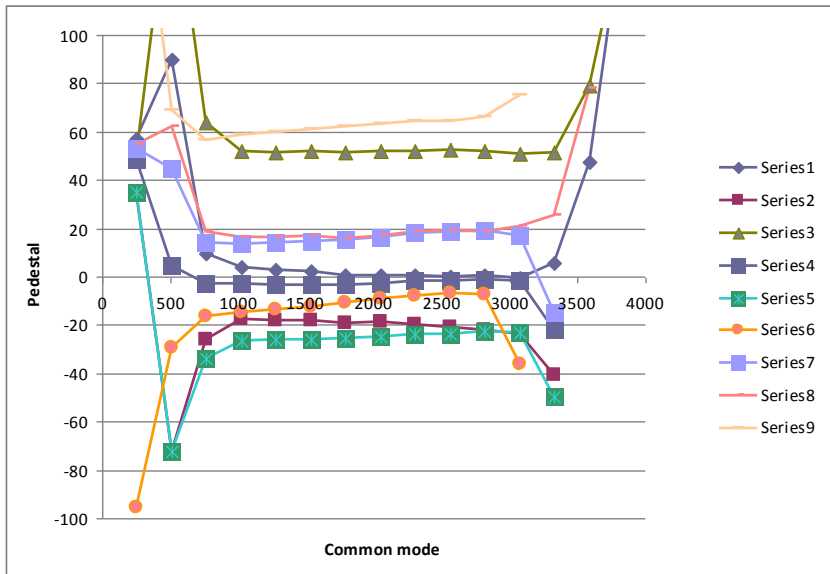


# Part III



# Threshold common mode

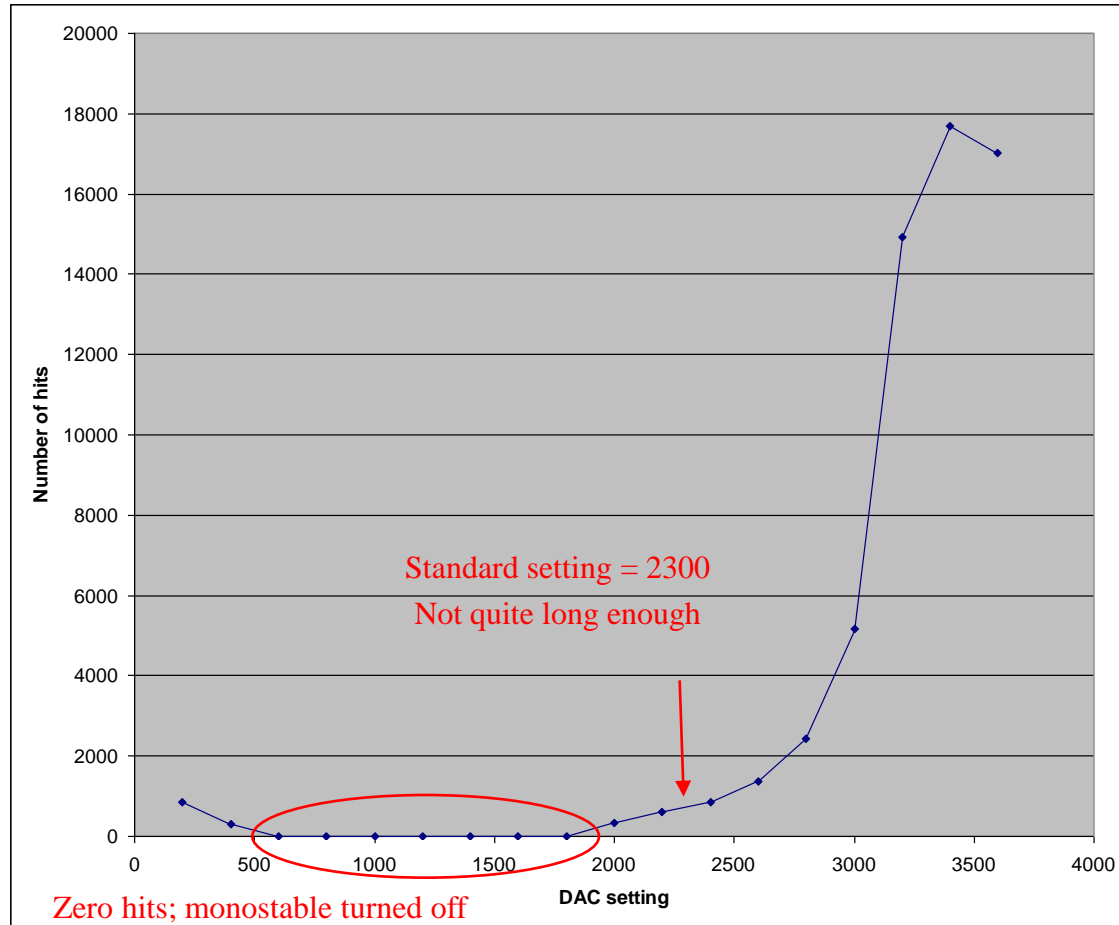
- Dependence of pedestal and noise on common mode setting
  - Checked for ten different pixels



- Wide sweet-spot in the middle; should stay in this region

# Monostables

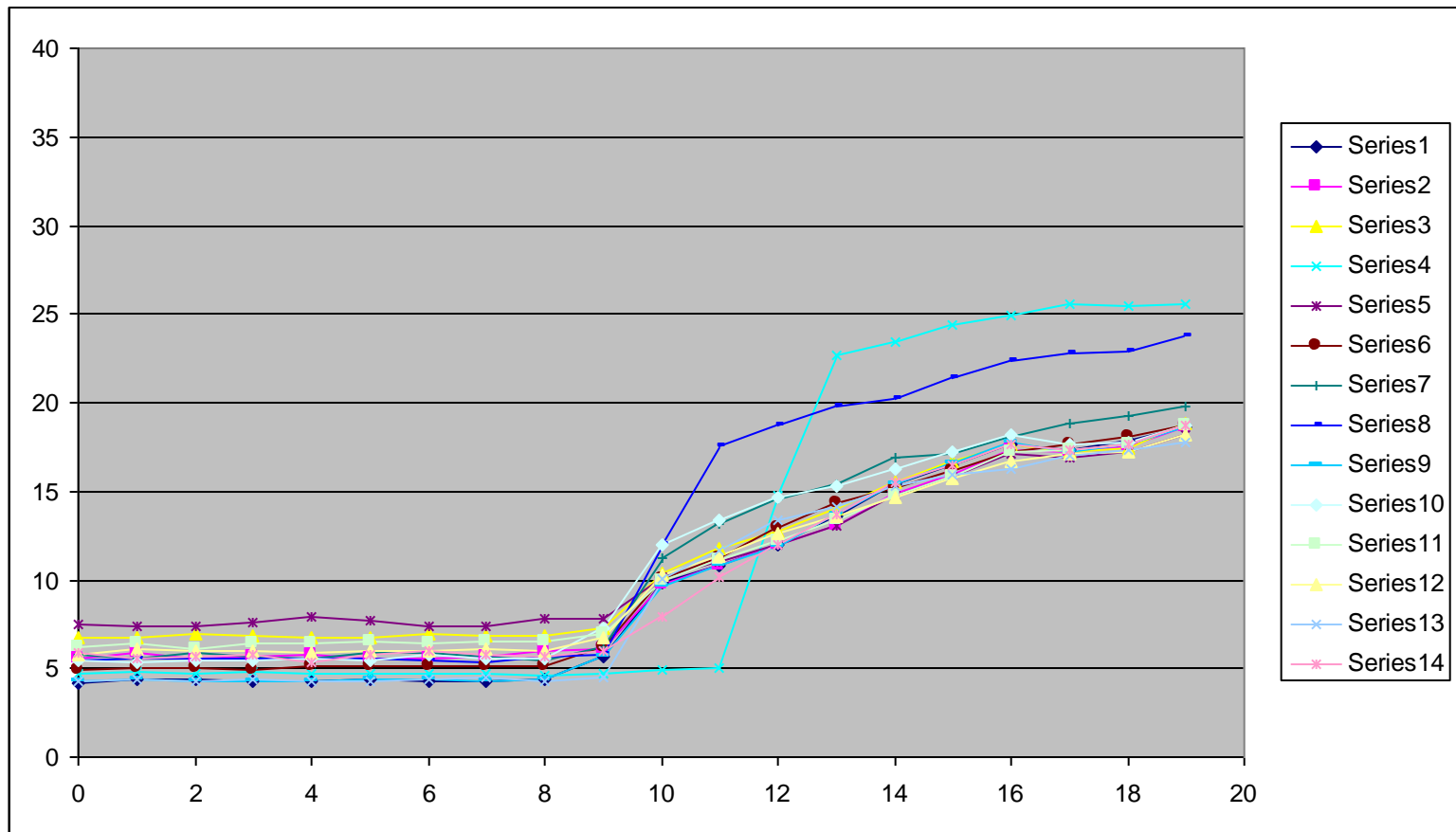
- Dependence of number of hits on monostable length
  - 1000 bunch trains so average must be  $> 1000$  for full efficiency





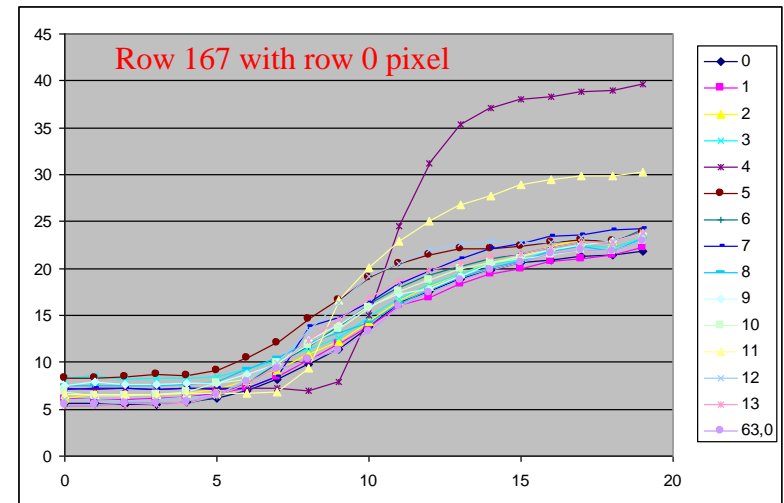
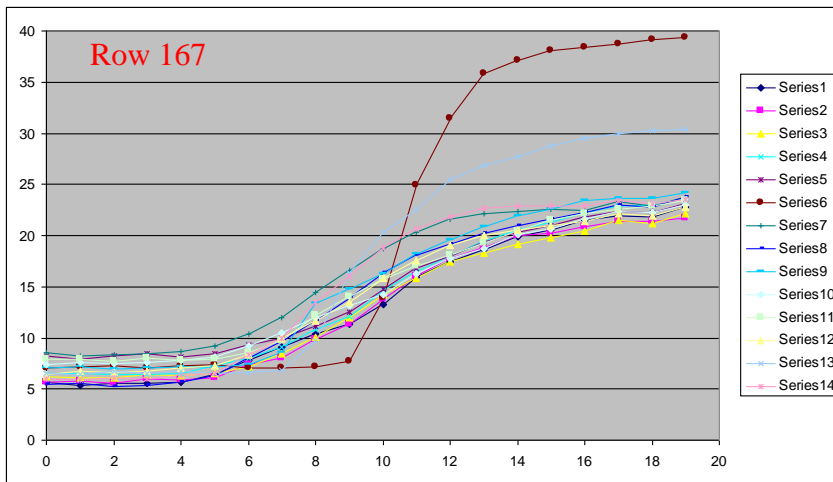
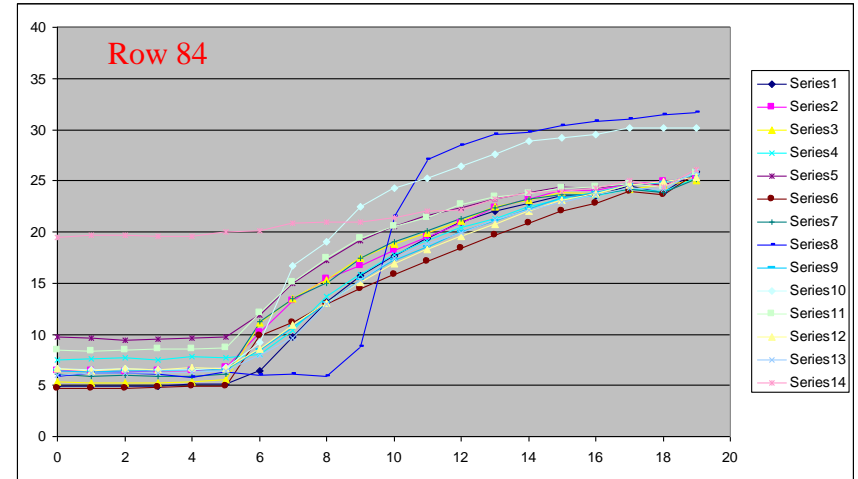
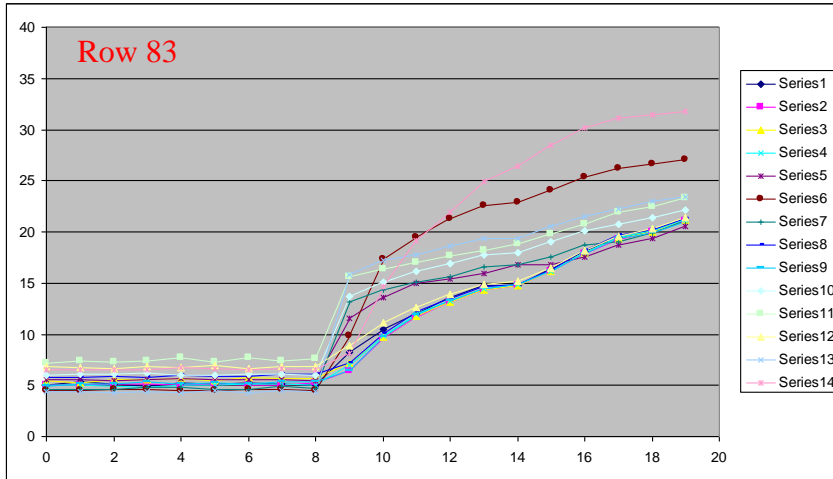
# Crosstalk

- Crosstalk depends on number of unmasked pixels
  - Reported by Jamie at FDR



Number of extra region 1 rows (= 42 pixels) enabled beyond region 1, row 0

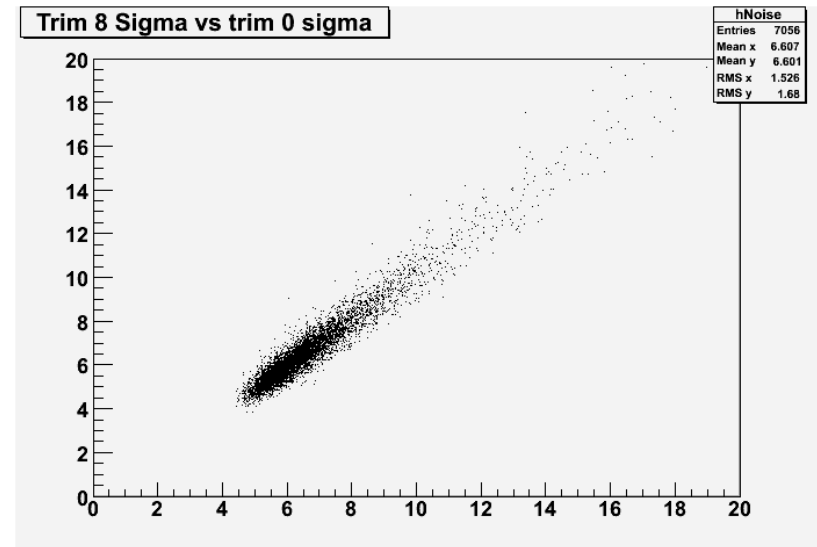
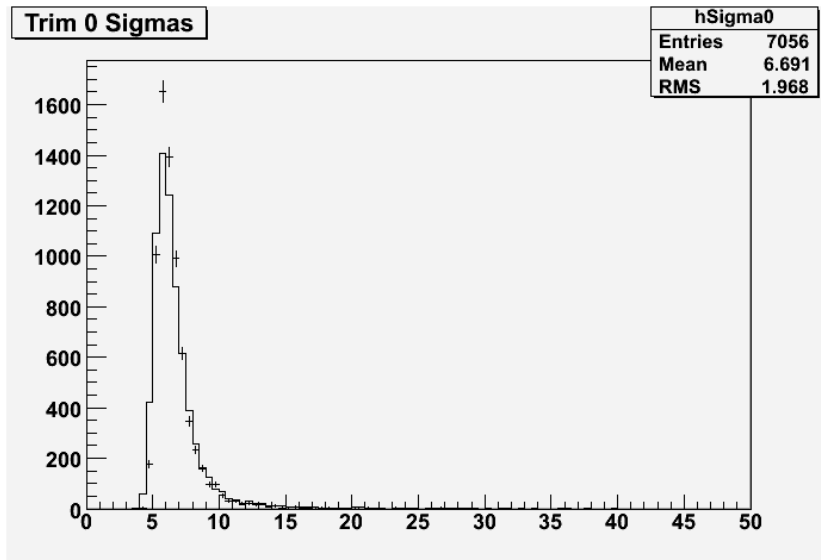
# Independent of location or proximity



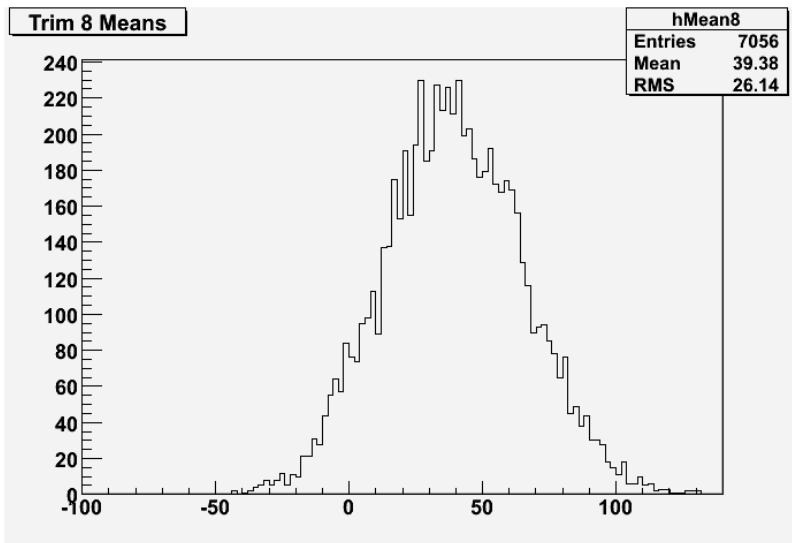
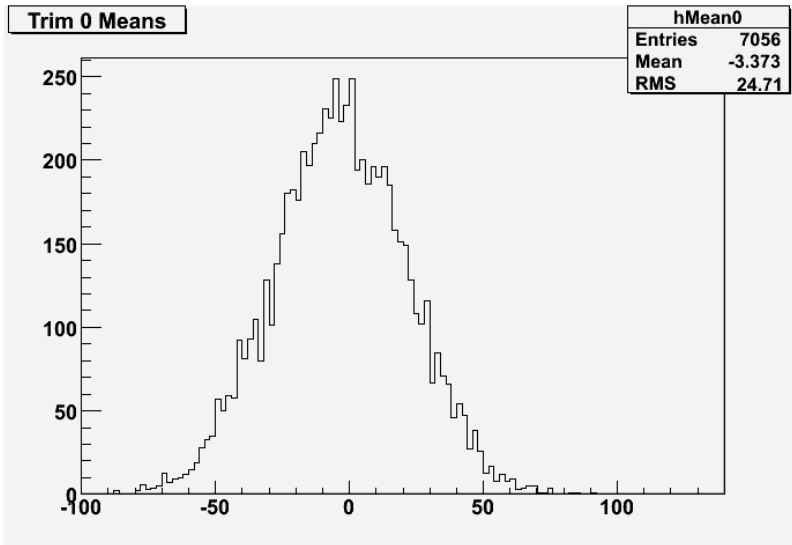
# Source setup

- Setting up second teststand at Imperial
  - Source tests in parallel with laser
- Need to trim sensor before running with source
  - Want to get lowest threshold without too much noise
- Threshold scan whole sensor in groups of 4 42 groups
  - One per region; below level of crosstalk
- Repeat with various trims

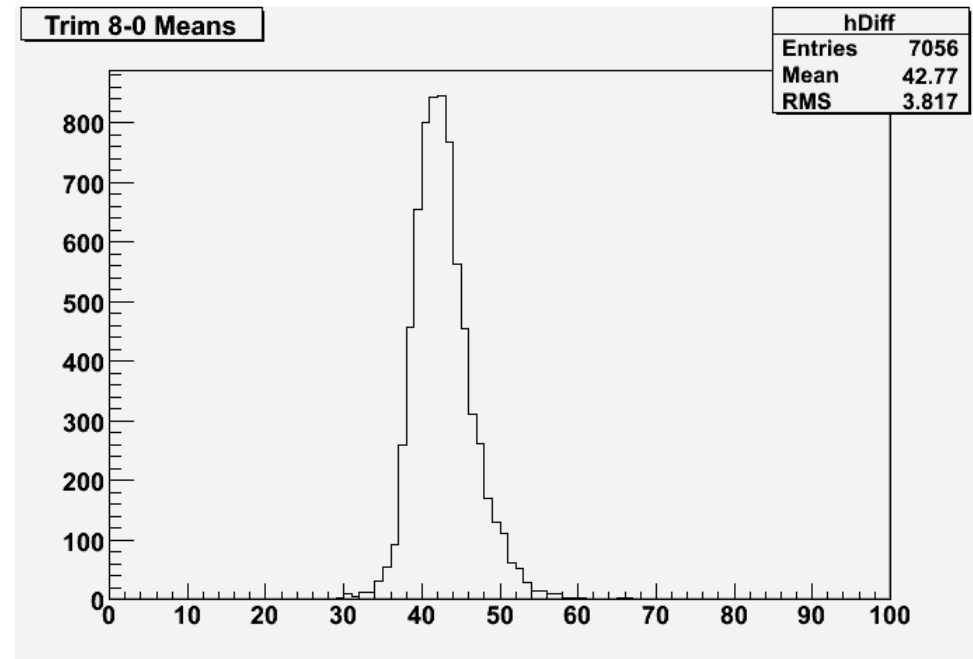
Sensor #10



# Trim range



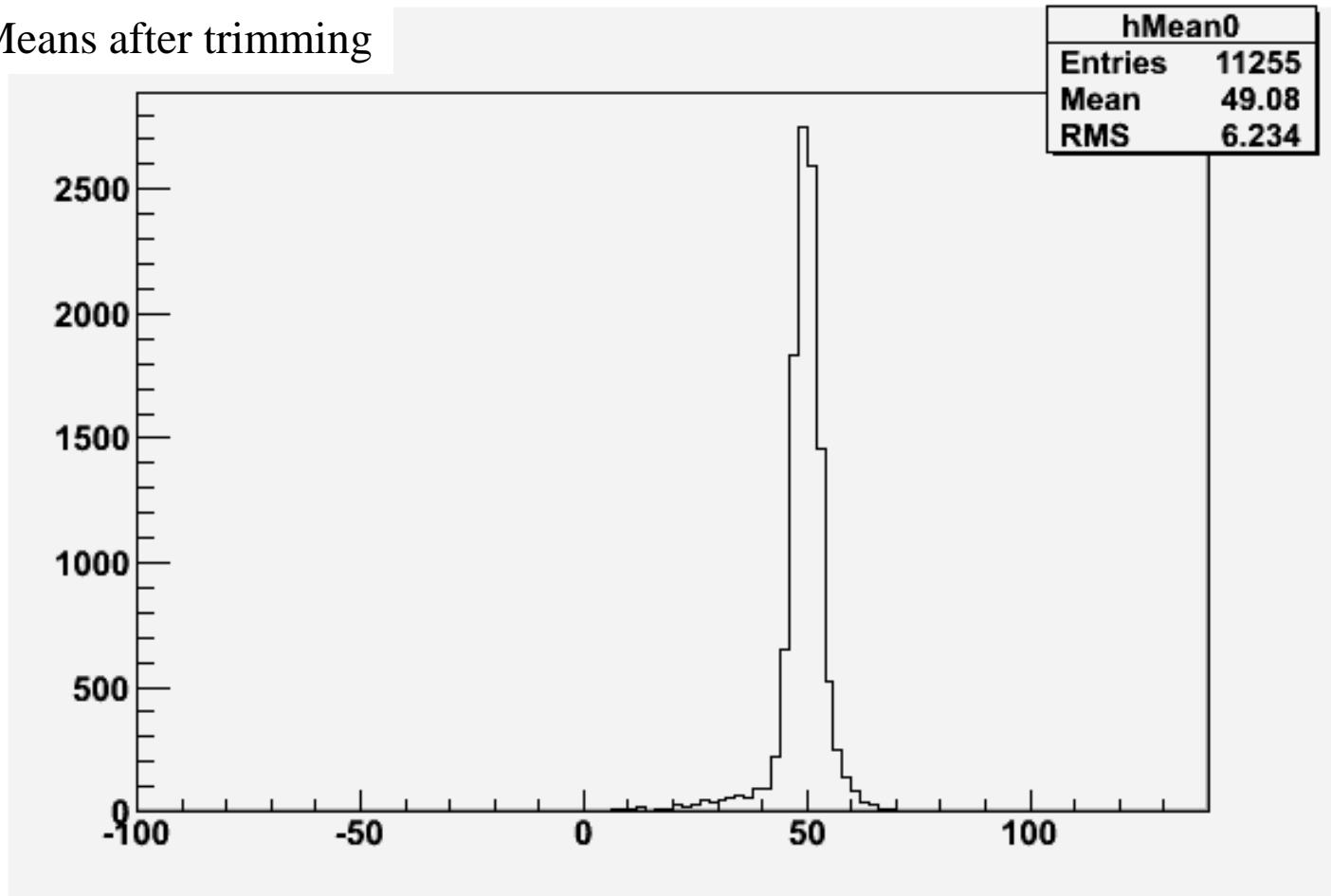
- Trim 0 to trim 8 shifts by  $\sim 40$  TU
  - Full range  $\sim 80$  TU
  - But spread is more like  $\sim 100$  TU
  - Needed to compromise on tails



# Trim range

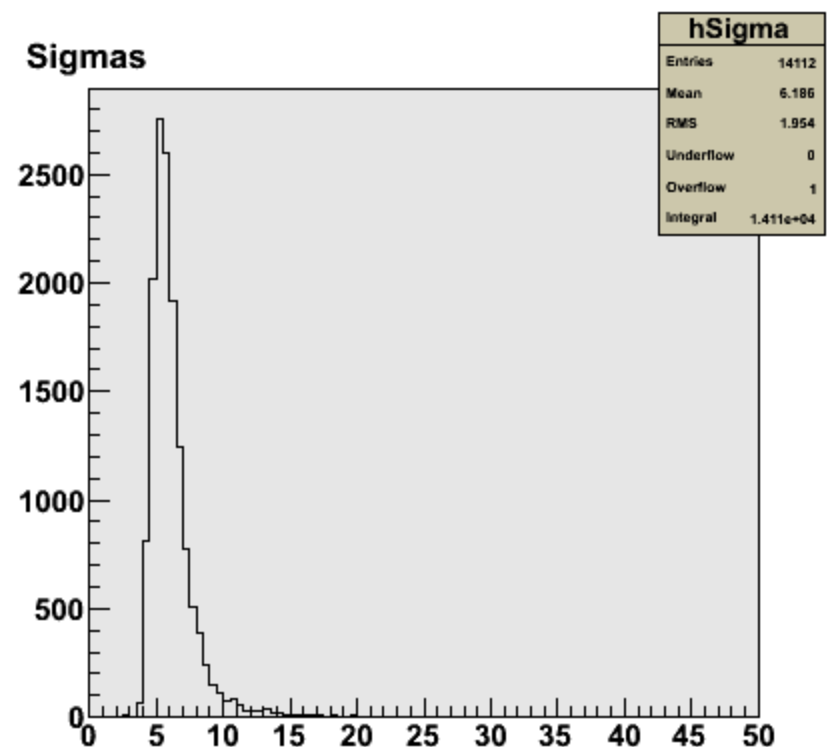
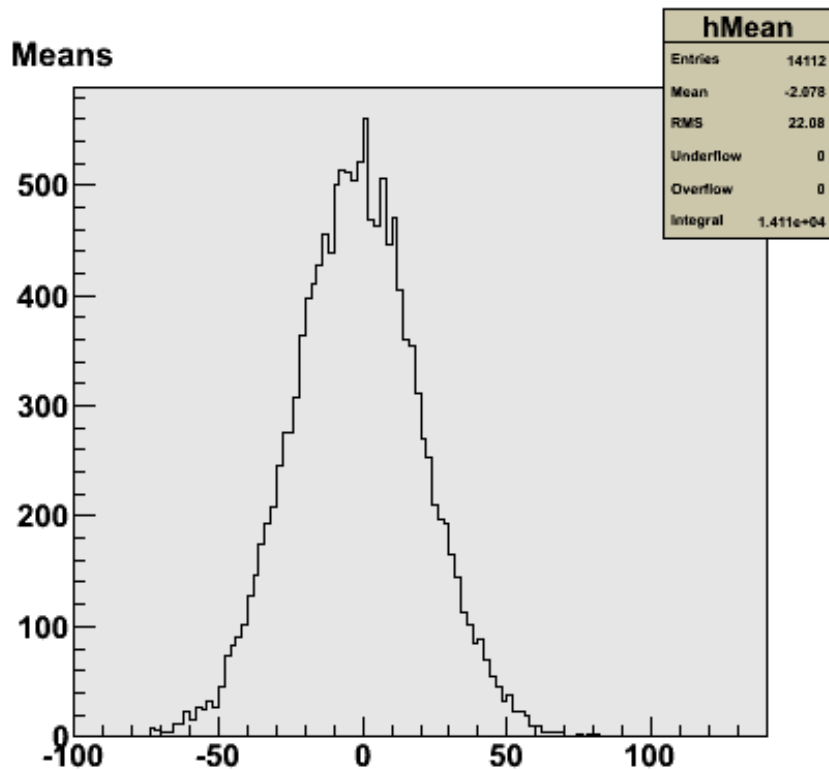
- Final distribution of shaper pedestals
- Be useful to compare with method with Owen's

Means after trimming



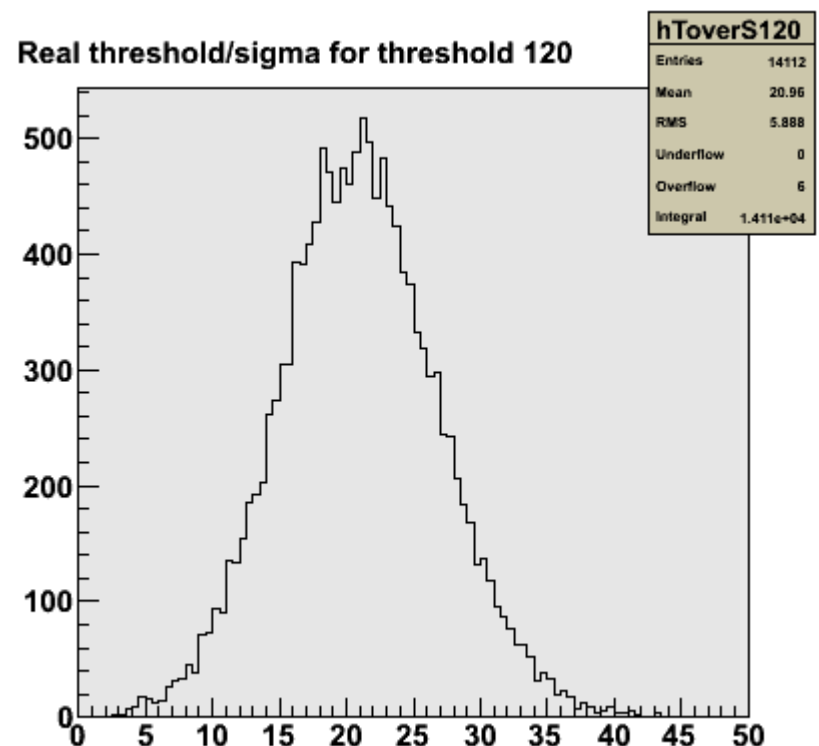
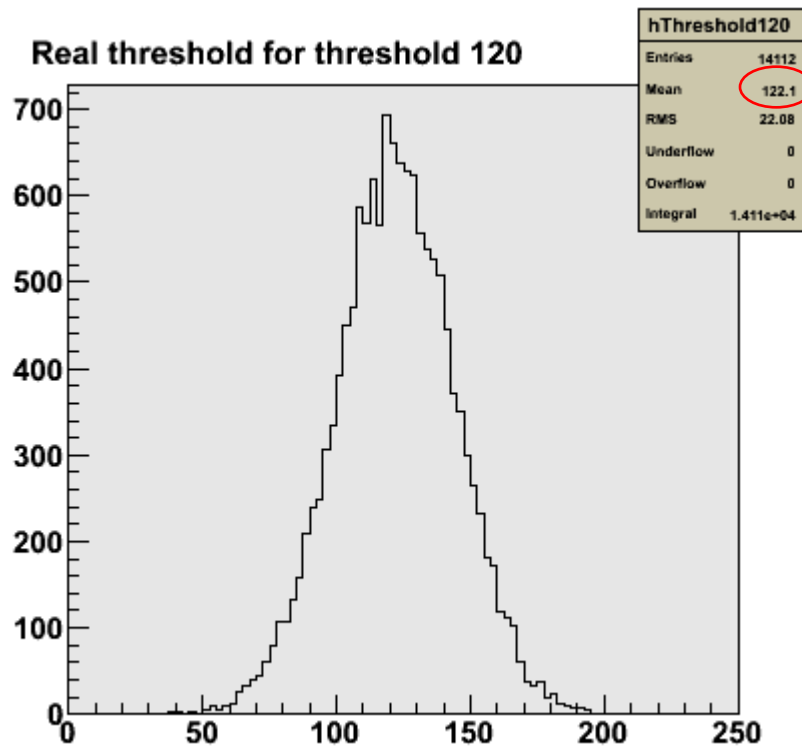
# Beam test revisited

- Use same technique to measure pedestals of sensor #7
  - One of the four used in the beam test stack
  - “Borrowed” Birmingham system before cosmics started
  - Did not adjust trims; beam data were all at trim=0



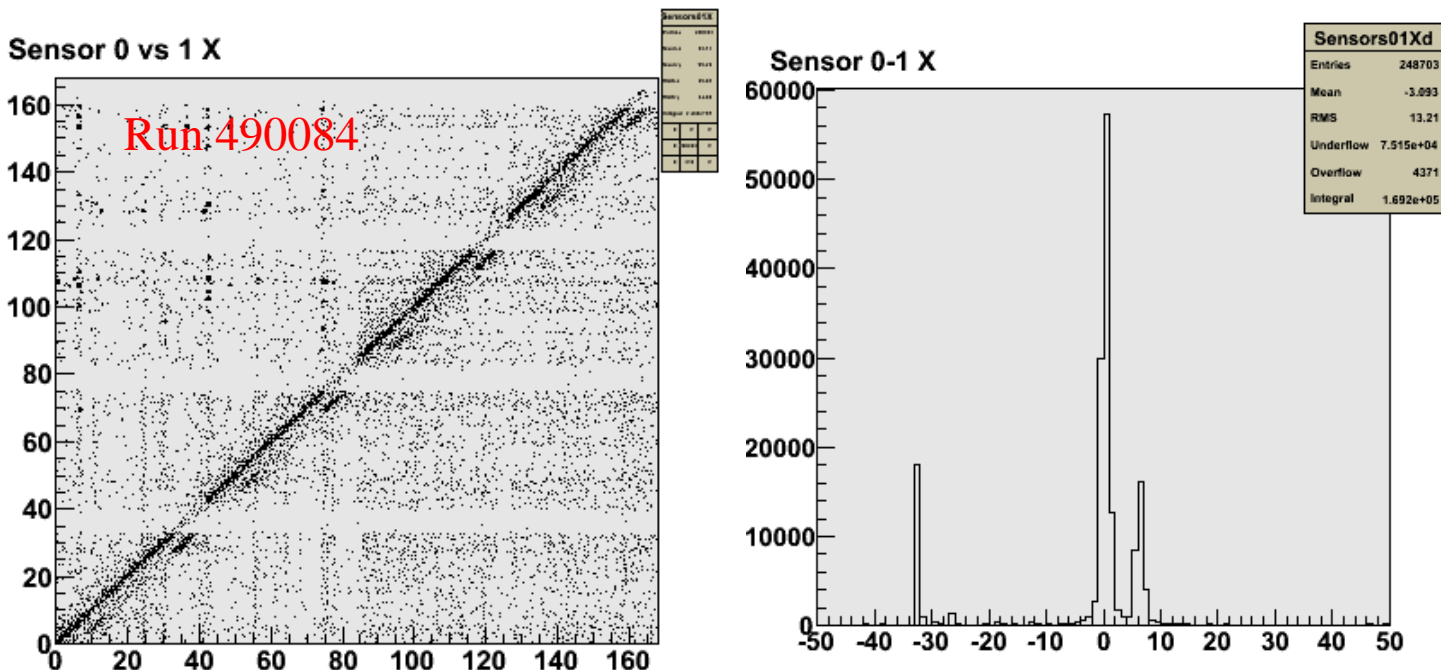
# Beam test real threshold

- Subtracting pedestal from general threshold gives “real” threshold setting per pixel
  - Assumes sensor #7 is unchanged since Dec



# Identifying real hits from tracks

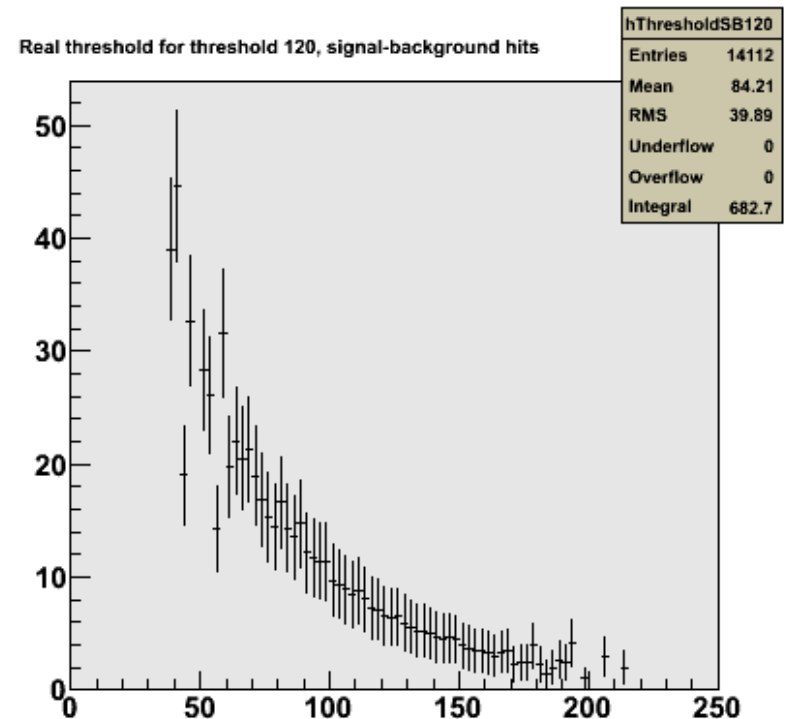
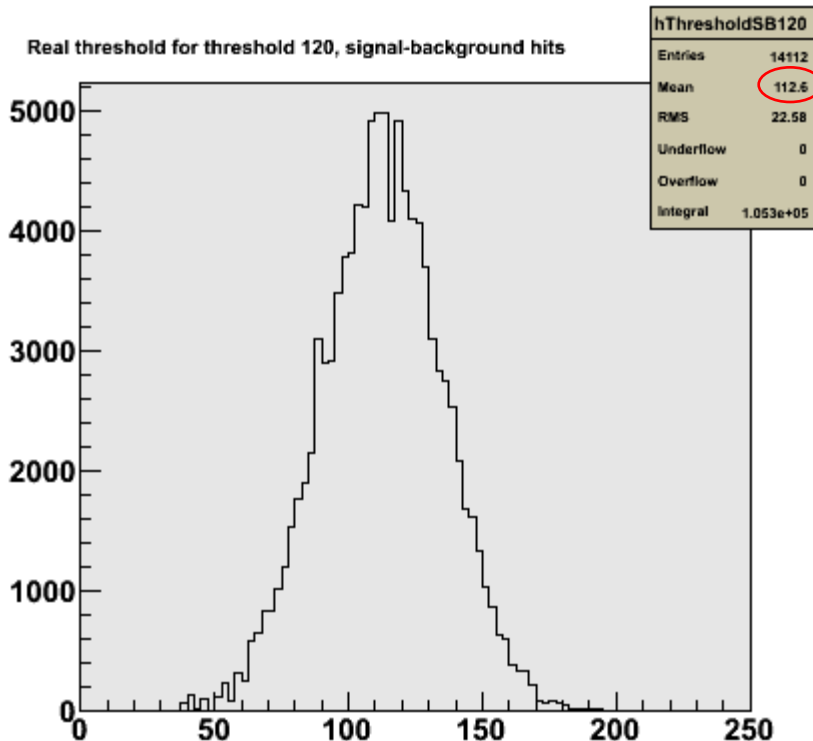
- Use simple x/y correlations, not full track reconstruction
  - Minimal alignment added for convenience
- Any hit matched in  $x \pm 2$ ,  $y \pm 2$  and  $t = 0$  to another layer is counted as real
  - Noise hits counted by matching in  $x$ ,  $y$  and  $t \pm 10$





# Real threshold of track hits

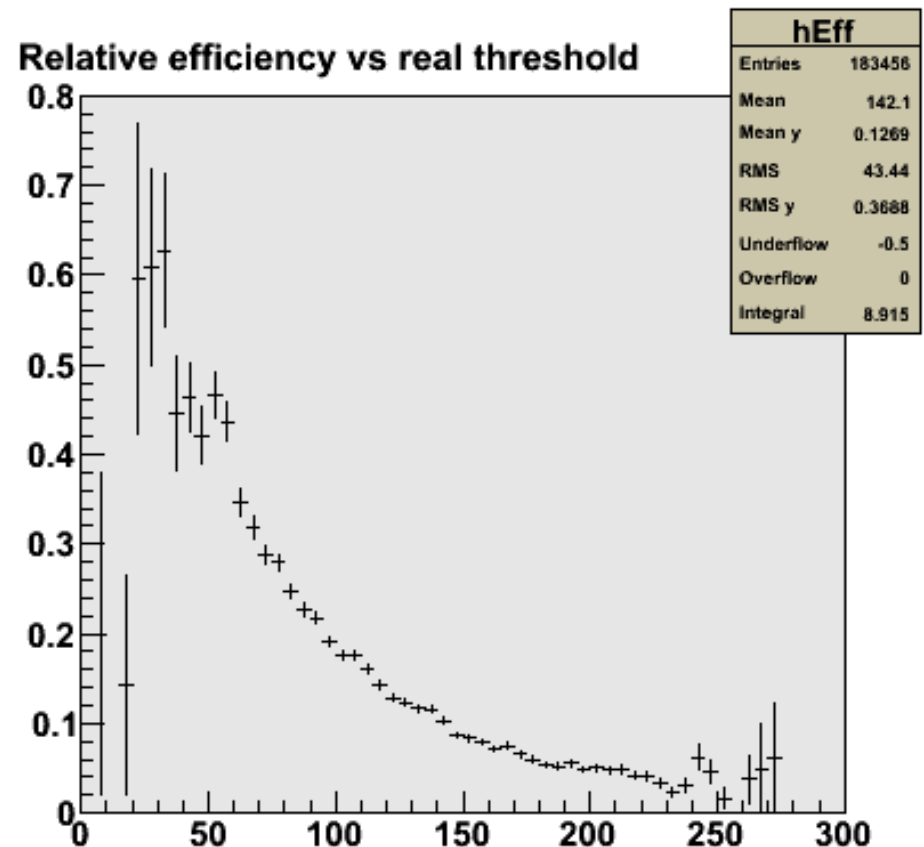
- Plot number of hits per pixel vs real threshold
- Dividing by original distribution gives relative efficiency
  - Assuming no correlation between real threshold and position, as shown by Owen



# Using threshold scan

- Use other threshold values to extend range
  - Different amount of data; divide threshold of 120 by factor 41 to get correct normalisation

- Take weighted average per real threshold
- Only gives relative efficiency; absolute normalisation would need quite a bit more work...



# Conclusions

- Working point is pretty optimal
  - Although should consider what to do with i12CompBias2
- Threshold common mode at 3072 is on the edge
  - Better to use the original 2048
- Monostable output is a bit short
  - Increase to 2600 for this channel studied
- Crosstalk kicks in with ~200-300 pixels enabled
  - Enabling less at a time allows whole sensor to be measured
- Relative efficiency from beam test looks measurable
  - Worth putting in more effort on this
  - Other sensors could be measured also